

Create, Embed, Empower

# **Automotive Competencies**

© Copyright Crevavi 2024

## Crevavi – Company Overview

A R&	D company, founded i	n 2011	Global footprint						
Automotive	EV / Autonomous	SW Functional Safety	Munich, Germany Bentonville, Arkansas; Belgaum Bangalore, India Mysore, India						
		torener tor							
Automotive ECU software	Inverter, OBC, DCDC BMS	ISO26262 compliance							
Company strengths									
developers 75+ HW Test benches	Actions + Actions + C 2 C C C C C C C C C C C C C	achin Shivapur o-founder and CEO 5 years experience Ravi Kishore Attili Co-founder and US Head 5 years experience hriram Kathavate Cofounder and CTO 3 years experience	<ul> <li>250+ Man years of Automotive ECU SW and HW experience</li> <li>HV EV ECU – Traction Inverter , DCDC, Battery Management (BMS), OBC</li> <li>R&amp;D for Automotive Electronics</li> <li>Functional safety (ISO26262)</li> <li>Development partners of major silicon vendors</li> <li>World-wide presence: India, Germany and USA</li> </ul>						
			Automotive software competencies						

## **Automotive Core competencies**



Crevavi

## Key ECU Projects executed



## ADAS: Real-time Object detection: using Jetson Nano

• Project: Implement Yolo algorithm on Jetson Nano for real-time object detection

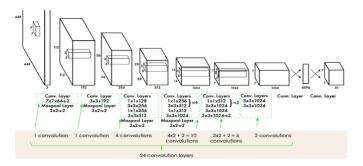
#### • Project content:

- Use the JetPack L4T BSP as base platform
- create pipeline and capture frames from the MIPI-CSI CSI camera using Gstreamer multimedia framework
- Integration of Yolo (You Only Look Once) CNN real-time object detection algorithm
- Integration of Pytorch tensor library for deep learning for Yolo algorithm
- Use the bounding boxes augmentation for object detection provided by Yolo
- Use the computing power of CUDA processors to render the image with minimal lag

#### • Customer Benefits :

- Optimize high compute loads on NVIDA platforms starting from Nano
  - quad-core 64-bit ARM CPU, a 128-core integrated NVIDIA GPU
- Validation of algorithms
- Performance and memory optimization for underlying hardware architecture



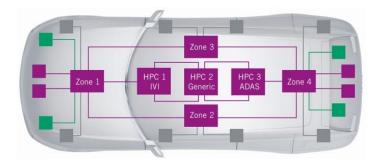


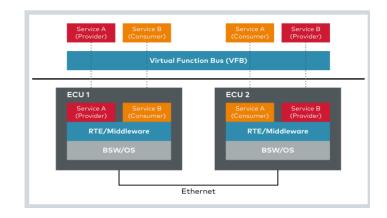


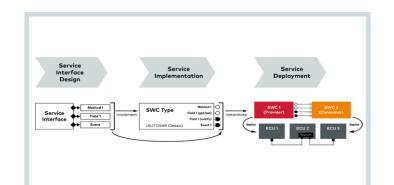
## Crevavi

## SW Defined Vehicle: SOA architecture for Body ECU

- Project content: Design SOA architecture for Body ECU components complaint to SOA
- Details:
  - Decode system requirements for Body ECU (Immobilizer, Climate, Alarm, Doors)
  - Design SOA architecture
    - SOA interaction within Body domain
    - SOA integration with Powertrain, Chassis, Cockpit domains and other Zonal ECUs
  - Arrive at safety goals following ISO26262 standard
    - For crash scenarios
    - Automatic door lock scenarios
  - SOA interaction between Zonal and HPC (high performance computing domains)
  - S2S (Signal to signal Adaptive AUTOSAR) design for communication across ECUs
  - Ethernet to CAN gateway interaction for SOA
- Customer Benefits
  - Leverage on SDV platform design experience
  - Leverage on SOA architecture definition for Zonal and HPC computing domains for SDV







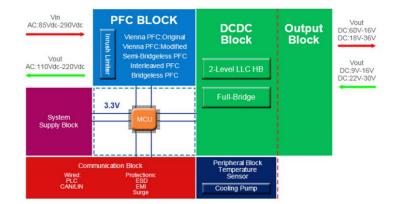
Creve

Image copyrights owned by Vector GmBH and SpringerLink

## E-Mobility: SW development for HV On-board Charger ECU

- Project content: CPU load reduction for AUTOSAR BSW stack on Multicore, Mixed ASIL ECU
- Details:
  - Entire Configuration analysis of AUTOSAR BSW and MCAL stack
  - Analysis of high frequency function calls and stacks
  - Profiling of start up, shutdown, communication (CAN-FD, LIN and **Ethernet**), OS Applications, spinlocks, memory and watchdog stacks
  - Validate and measurement of CPU loads reduction and memory optimization
  - Verify NVM(D-Flash), wakeup, Ethernet, SOMEIP configuration for SOP
  - Write and validate microcontroller functional safety drivers to be compliant with ISO26262
  - Achieve ASIL-D safety concept
    - FCCU configuration, CRC, Memory error management and reporting of events
  - Validate multi-core, mixed-ASIL functionality
    - Memory and core partioning
- ECU HW
  - ST SPC58 Chorus family
  - e200z4 triple core:32-bit Power Architecture technology CPU









# E-Mobility: DCDC and SCAP ECU for Anti-roll ECU

- Ask from Indian Supplier
  - Operate in BOT model + Manage project timelines and deliverables
  - Deliver series grade project for a Japanese Tier1 for HV EV DCDC and Super-capacitor ECU
  - Handle UK OEM interactions
- Project: Configure AUTOSAR BSW stack for Anti-roll ECU (DCDC and Super Capacitor ECU)
- Project work carried out:
  - Configuration and integration of Vector AUTOSAR BSW stack and Bootloader
  - Develop Complex Drivers
  - Cell-balancing Complex Driver for Super Capacitors
  - End-to-end system testing for series production
- Customer Benefits :
  - Demonstrated End-to-end systems' competency in HV DCDC converter SW
  - Provided entire ECU SW architecting as a consultancy to Tier1 and OEMs
  - Own entire validation responsibility for series production





Super Capacitors on the ECU



Anti-roll System



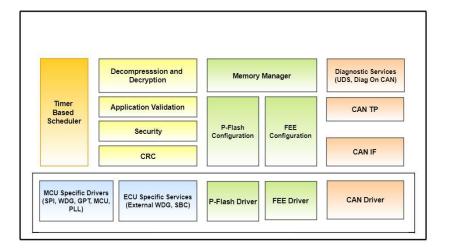
## Migrate TCU platform from NXP to Infineon AURIX for American Tier1

- Ask from German Supplier (Partner)
  - Bid for the TCU (Transmission control Unit) project and win against competitors
  - Own end-to-end execution of project
  - Handle Japanese OEM interactions on behalf of American Tier1
- Project: Develop Generic Bootloaders for Transmission control system ECUs
- Project work carried out:
  - Integration of legacy SW, middle-ware, AUTOSAR select layers and MCAL(IO)
  - Development of Generic bootloader
  - Development of state-of-the-art security algorithms
  - Handle OEM interactions
  - **Customer Benefits :**

٠

- Develop robust platform ECU for scalability
- Upto 50% reduction in TTM and TCC (total cost of ownership)
- Offload Tier1s with OEM interactions
- Meet stringent SOP requirements of global OEMs(Japanese, European and US)





Legend:	Communication Modules	Memory Modules	Scheduler
	Software Utilities	Other Modules	
			Grevov

# Flash Bootloaders (FBL) for Aurix TC2XX

- Project: Develop Generic Bootloaders for Transmission control system ECUs
  - End-to-end responsibility from concept to production
  - MCAL stack using EB Tresos
  - Vector CAN Stack (CAN Driver, CANIF, CANSM) using DAVINCI Configurator tool
  - Compliance to ISO 14229-1 and ISO 15765-2 (UDS on CAN)
  - Develop flashing using XCP protocol
  - Support for ODX flash specifications

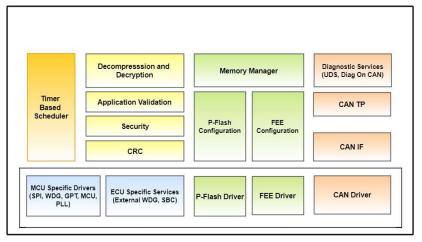
- Customer Benefits :
  - Develop platform for scalability
  - Pragmatic implementation of 3<sup>rd</sup> party IP to save royalty costs
  - Upto 50% reduction in TTM
  - Upto 50% reduction in total cost of ownership

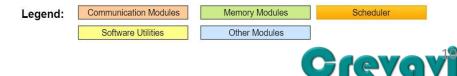








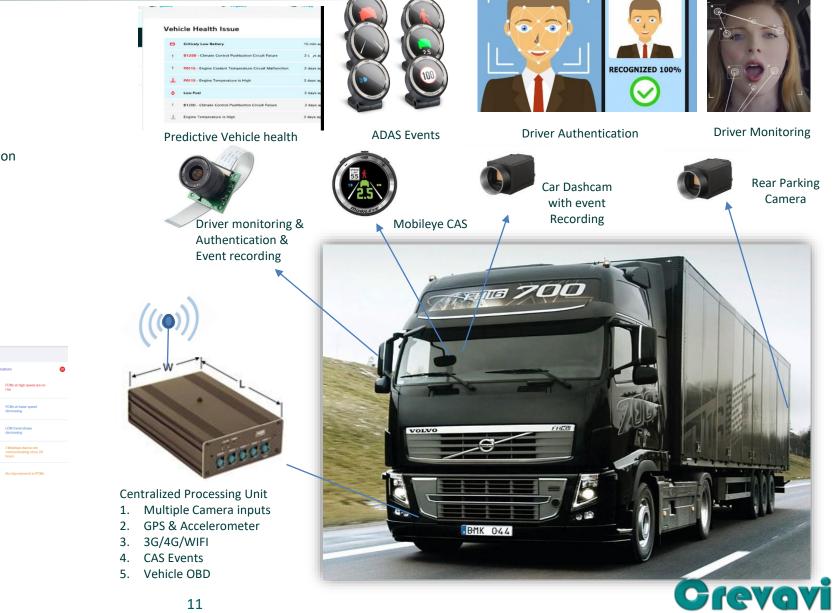




# **Telematics and ADAS platform with Intel**







11

#### **Project Content:**

- Linux based platform co-developed with Intel ٠
- OBDII, GSM communication on Intel Atom ٠
- Fleet Management System (FMS) on cloud •
- Interface with ADAS processor for ADAS event recognition .
- Connects to cloud via cellular modem •
- Integrated GNSS for tag and trace .
- **OBDII** connection using UDS protocol ٠

© Copyright Crevavi 2024 Confidential Internal document

#### **Customer Benefits :**

- Ready platform for FMS, Telematics and ADAS .
- Retrofit and factory fit option ٠

(intel)	ាក្រ Dashboar	d 🗇 Fleet	요 Drivers 🛆	Violations ⓒ De Press F11 to exit t	wices 😗 💷 Ana	alytics 🖗 Anomalies		
Stats Maps								
Today This week	This month Last 3 month	This year				5 Top 5 Drivers		lotifications
5         132         20         10%         402         39         Monry         346         40         10         400         20         Fill         Monry         400         36         With Moldays           Accelerits         Accelerits         Accelerits         Mobilitye Devices         Whiteles         Whiteles         Whiteles					Andrew Castilla 4.8 Car: Toyota Corolla Status: Me	•	FCWs at high speed are or rise	
		,,				John Christopher 4.5 Car: Skoda R Status: Driving	•	FCWs at lower speed decreasing
hlita	hhild			hhilli	hth	Robert Zane 42 Car: Hyundai 020 Status: Driving	•	LDW trend shows decreasing
103 Probable Vehicle Accidents Avoided 29 Probable Pedestrian Accidents Avoided				Adom Lawrence 47 Car: Toyota Corolla Status: Driving	•	1 Mobileye device not communicating since 24 hours		
Pedestrian collision warnings	Forward collision warnings	Lane departure warnings	Hard breaking	Hard acceleration	Hard curving	John Christopher 4.0 Car: Toyota Corolla Status: Me	•	No improvement in PCWs
Decreased	Increased	Increased	Decreased	Increased	Increased	5 Bottom 5 Drivers		
20 Kmph 5% 🗸 40 Kr	nph 27% 🔺 60 Kmph 19% 🗸	80 Kmph 16% ^ 100 h	Kmph 38% 🗸 120+ Kmph 2	26% 🗸		Robert Zane 2.8 Car: Hyundai i20 Status: Driving	•	
Lhr.			l.hr.			Adom Lawrence 22 Car: Toyota Corolla Status: Driving	•	
Probable Vehicle.			2 Drobable Dedestri	ian Accidents Occurred		Andrew Castilla 2.8 Car: Toyota Corolla Status: Idio	•	
FCW - Forward Collision Wa		ing I DW - Lane Departure V	Varning PCW - Pedestrian Co		relevation	John Christopher 2.0 Car: Skoda R	•	

## Immobilizer ECU for Indian Tier1

- Ask from an Indian Supplier
  - Bag the project from the European OEM. Win the bid against competitors
  - Deliver a generic platform immobilizer ECU
- **Project:** Develop the entire ECU SW for a renowned European sports bikes manufacturer
- Project content:
  - Develop bootloader and UDS diagnostics stack
  - Key authentication with key transponder, Pairing with Immobilizer and Engine ECU
  - State-of-the-art encryption and decryption algorithms as defined by German supplier
- Customer Benefits :
  - Leverage on Immobilizer domain knowhow
  - Meet demanding TTM timelines
  - Bootloader with state-of-the-art security algorithms











## Instrument Cluster ECU

- Project: Develop IO drivers for Renesas RH850 controller
- Challenge: Deliver ECU software in 5 months from scratch using newly launched controller
- Project content:
  - Develop AUTOSAR like ADC, PWM, I2C, RTC, WDT, SOUND, DMA drivers
  - Compliance to SW layered architecture of AUTOSAR
  - Portable across Renesas RH850 family
- **Customer Benefits :** 
  - RH850 controller know-how to meet demanding TTM targets
  - Instrument cluster domain know
  - Platform development for scalability

# 3 4 2 9 1 0 0 5 0 0 1 0 0 5 0







## Powertrain ECU software

- 20 years of automotive powertrain ECU software development
  - TPU and PCP co-processor programming for time critical applications like injection and ignition
  - End power-stage control and diagnosis of actuators
  - CAN, UDS, KWP, LIN communication protocols development
  - Layered SW architecture development on the lines of AUTOSAR standards
- Quality process\methodology
  - ASPICE process compliance
  - FMEA and 8D analysis
  - ISO26262 compliance
  - DevOPs / CICD
- Customer Benefits
  - SW development for highest ASIL ISO2626 applications
  - Multicore Mixed ASIL
  - Time critical applications requiring complex timing waveform generation

14









## Thank You for your time

Sachin Shivapur Co-Founder & CEO Germany: +49-160-1479 707 sachin.shivapur@crevavi.com

Shriram Kathavate Co-founder & CTO India: +91-9880167217 Shriram.Kathavate@crevavi.com

### WWW.MOBILITY.CREVAVI.COM WWW.CREVAVI.COM

